

### **Geometric Transformations**

### **Two-Dimensional Transformations**

A graphic system should allow the programer to define pictures that include a variety of transformations. For example, he should be able to magnify a picture so that detail appears more clearly, or reduce it so that more of the picture is visible.

Transformation: is a single mathematical entity and as such can be denoted by a single name or symbol (translation, rotation, or scaling). Each of these transformations is used to generate a new point ( $\bar{x}$ ,  $\bar{y}$ ) from the coordinates of a point (x,y) in the original picture description. If the original definition includes a line, it suffices to apply the transformation to the endpoints of the line and display the line between the two transformed endpoints.

#### 1- Translation:

The form of translation transformation is:

$$\overline{x} = \mathbf{x} + \mathbf{T}_{\mathbf{x}}, \quad \overline{y} = \mathbf{y} + \mathbf{T}_{\mathbf{y}}$$

Translation transformation can be represented in a uniform way by a  $3 \times 3$  matrix as shown below:

$$\begin{bmatrix} \bar{x} & \bar{y} & 1 \end{bmatrix} = \begin{bmatrix} x & y & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ Tx & Ty & 1 \end{bmatrix}$$

#### Example:

Consider triangle defined by its three vertices (20,0), (60,0), (40,100) being translated 100 units to the right and 10 units up. What are the new vertices?

T<sub>x</sub>=100, T<sub>y</sub>=10



The new vertices are:

 $(20,0) \rightarrow (20+100,0+10) \rightarrow (120,10)$ (60,0)  $\rightarrow (60+100,0+10) \rightarrow (160,10)$ (40,100)  $\rightarrow (40+100,100+10) \rightarrow (140,110)$ or:

$$\begin{bmatrix} \overline{x} & \overline{y} & 1 \end{bmatrix} = \begin{bmatrix} 20 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 100 & 10 & 1 \end{bmatrix} = \begin{bmatrix} 120 & 10 & 1 \end{bmatrix}$$
$$\begin{bmatrix} \overline{x} & \overline{y} & 1 \end{bmatrix} = \begin{bmatrix} 60 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 100 & 10 & 1 \end{bmatrix} = \begin{bmatrix} 160 & 10 & 1 \end{bmatrix}$$
$$\begin{bmatrix} \overline{x} & \overline{y} & 1 \end{bmatrix} = \begin{bmatrix} 40 & 100 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 100 & 10 & 1 \end{bmatrix} = \begin{bmatrix} 140 & 110 & 1 \end{bmatrix}$$

### <u>H.W</u>.: Draw the vertices of the above example before and after the translation?

#### 2- Rotation:

To rotate a point (x,y) through a clockwise angle  $\theta$  about the origin of the coordinate system, we write:

 $\overline{x} = \mathbf{x} \cos \theta + \mathbf{y} \sin \theta$ ,  $\overline{y} = -\mathbf{x} \sin \theta + \mathbf{y} \cos \theta$ 

Rotation transformation can be represented in a uniform way by a 3×3 matrix as shown below:

 $\begin{bmatrix} \overline{x} & \overline{y} & 1 \end{bmatrix} = \begin{bmatrix} x & y & 1 \end{bmatrix} \begin{bmatrix} \cos\theta & -\sin\theta & 0 \\ \sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$ 

#### Example:

Consider triangle defined by its three vertices (20,0), (60,0), (40,100) being rotated  $45^{\circ}$  clockwise about the origin. What are the new vertices?



The new vertices are:

$$\begin{array}{rcl} (20,0) &\to& \overline{x} = 20\cos 45 + 0\,\sin 45 = 14.14 \\ &\to& \overline{y} = -20\sin 45 + \,0\,\cos 45 = -14.14 \\ &\to& (14.14,\,-14.14) \\ (60,0) &\to& \overline{x} = 60\cos 45 + 0\,\sin 45 = 42.43 \\ &\to& \overline{y} = -60\sin 45 + \,0\,\cos 45 = -42.43 \\ &\to& (42.43,\,-42.43) \\ (40,100) &\to& \overline{x} = 40\cos 45 + 100\,\sin 45 = 98.99 \\ &\to& \overline{y} = -40\sin 45 + \,100\,\cos 45 = 42.43 \\ &\to& (98.99,\,42.43) \end{array}$$

or:

$$\begin{bmatrix} \overline{x} & \overline{y} & 1 \end{bmatrix} = \begin{bmatrix} 20 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos 45 & -\sin 45 & 0 \\ \sin 45 & \cos 45 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 14.14 & -14.14 & 1 \end{bmatrix}$$
$$\begin{bmatrix} \overline{x} & \overline{y} & 1 \end{bmatrix} = \begin{bmatrix} 60 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos 45 & -\sin 45 & 0 \\ \sin 45 & \cos 45 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 42.43 & -42.43 & 1 \end{bmatrix}$$
$$\begin{bmatrix} \overline{x} & \overline{y} & 1 \end{bmatrix} = \begin{bmatrix} 40 & 100 & 1 \end{bmatrix} \begin{bmatrix} \cos 45 & -\sin 45 & 0 \\ \sin 45 & \cos 45 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 98.99 & 42.43 & 1 \end{bmatrix}$$

<u>H.W</u>.: Draw the vertices of the above example before and after the rotation?

#### 3- Scaling:

The form of the scaling transformation is:

$$\overline{x} = \mathbf{x} \mathbf{S}_{\mathbf{x}}, \quad \overline{y} = \mathbf{y} \mathbf{S}_{\mathbf{y}}$$

The scaling transformation can be used for a variety of purposes. If the picture is to be enlarged to twice it's original size we might choose  $S_x=S_y=2$ . Notice that the elargement is relative to the origin of the coordinate system.



scaling transformation can be represented in a uniform way by a  $3 \times 3$  matrix as shown below:

$$\begin{bmatrix} \bar{x} & \bar{y} & 1 \end{bmatrix} = \begin{bmatrix} x & y & 1 \end{bmatrix} \begin{bmatrix} Sx & 0 & 0 \\ 0 & Sy & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Example:

Consider triangle defined by it's three vertices (20,0), (60,0), (40,100) being twice enlarged.. What are the new vertices?

S<sub>x</sub>=S<sub>y</sub>=2

The new vertices are:

 $(20,0) \rightarrow (20 \times 2, 0 \times 2) \rightarrow (40,0)$ (60,0)  $\rightarrow (60 \times 2, 0 \times 2) \rightarrow (120,0)$ 

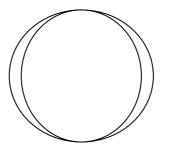
 $(40,100) \rightarrow (40 \times 2,100 \times 2) \rightarrow (80,200)$ 

or:

$$\begin{bmatrix} \overline{x} & \overline{y} & 1 \end{bmatrix} = \begin{bmatrix} 20 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 40 & 0 & 1 \end{bmatrix}$$
$$\begin{bmatrix} \overline{x} & \overline{y} & 1 \end{bmatrix} = \begin{bmatrix} 60 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 120 & 0 & 1 \end{bmatrix}$$
$$\begin{bmatrix} \overline{x} & \overline{y} & 1 \end{bmatrix} = \begin{bmatrix} 40 & 100 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 80 & 200 & 1 \end{bmatrix}$$

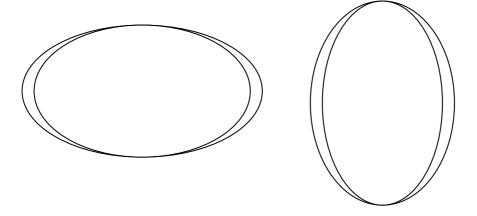
# <u>H.W</u>.: Draw the vertices of the above example before and after the scaling?

Note: If  $S_x$  and  $S_y$  are not equal, they have the effect of distorting pictures by elongating or shrinking them along the directions parallel to the coordinate axes. For instance the foolowing figure:





#### Can be distorted as shown in figures below:



4- Reflection (Mirroring):

Reflection transformation can be considered as a special case of scaling, because the mirror image of an object can be generated using negative values of  $S_x$  or  $S_y$ . Mirror images of figure below:



Can be generated as shown below:

$$\bar{x} = \mathbf{x}(-\mathbf{S}_{\mathbf{x}}), \quad \bar{y} = \mathbf{y}\mathbf{S}_{\mathbf{y}}$$

$$[\bar{x} \quad \bar{y} \quad 1] = [x \quad y \quad 1] \begin{bmatrix} -Sx & 0 & 0 \\ 0 & Sy & 0 \\ 0 & 0 & 1 \end{bmatrix}$$



$$\overline{x} = \mathbf{x} \mathbf{S}_{\mathbf{x}}, \quad \overline{y} = \mathbf{y}(-\mathbf{S}_{\mathbf{y}}) \qquad \qquad [\overline{x} \quad \overline{y} \quad 1] = [x \quad y \quad 1] \begin{bmatrix} Sx & 0 & 0 \\ 0 & -Sy & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\bar{x} = \mathbf{x}(-\mathbf{S}_{\mathbf{x}}), \ \bar{y} = \mathbf{y}(-\mathbf{S}_{\mathbf{y}})$$

$$[\bar{x} \ \bar{y} \ 1] = [x \ y \ 1] \begin{bmatrix} -Sx & 0 & 0 \\ 0 & -Sy & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

<u>H.W</u>.: Write complete program in order to perform all types of transformations on a line between (0,1) and (5,6)?

#### Example:

The triangle with vertices ((20,0),(60,0),(40,100)) is rotated through 90<sup>0</sup>, and then translated with T<sub>x</sub>=-80,T<sub>y</sub>=0. What is the new vertices of the resulted figure?

**Rotation:** 

 $\bar{x} = \mathbf{x} \cos\theta + \mathbf{y} \sin\theta = \mathbf{x} \cos 90 + \mathbf{y} \sin 90 = \mathbf{y}$ 

$$\overline{y}$$
 = - x sin $\theta$  + y cos $\theta$  = - sin90 + y sin90= -x

**Translation:** 

$$\bar{x} = \bar{x} + T_x = y - 80$$
  
 $\bar{y} = \bar{y} + T_y = -x$   
then:  
(20.0):  $\bar{x} = x - 80 = 0.80 = 80$   $\bar{x} = x = 20 + (.80, 20)$ 

(20,0): 
$$x = y - 80 = 0.80 = .80$$
,  $y = .x = .20 \rightarrow (-80, -20)$   
(60,0):  $\bar{x} = y - 80 = 0.80 = .80$ ,  $\bar{y} = .x = .60 \rightarrow (-80, -60)$ 



(40,100): 
$$\bar{x} = y - 80 = 100 - 80 = 20$$
,  $\bar{y} = -x = -40 \rightarrow (20, -40)$ 

## <u>H.W</u>.: Draw the vertices of the above example before and after the scaling?

#### Example:

Perform a  $(45^{\circ})$  rotation of triangle A(0,0), B(1,1), C(5,2) about the origin using matrix representation?

Representation of triangle:
$$\begin{bmatrix} 0 & 1 & 5 \\ 0 & 1 & 2 \\ 1 & 1 & 1 \end{bmatrix}$$

Rotation matrix= 
$$\mathbf{R}_{45} = \begin{bmatrix} \cos 45 & -\sin 45 & 0 \\ \sin 45 & \cos 45 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} & 0 \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0 \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Then:

$$\begin{bmatrix} \overline{A} & \overline{B} & \overline{C} \end{bmatrix} = R_{45} \times \begin{bmatrix} A & B & C \end{bmatrix} = \begin{bmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} & 0 \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 1 & 5 \\ 0 & 1 & 2 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & \frac{3\sqrt{2}}{2} \\ 0 & \sqrt{2} & \frac{7\sqrt{2}}{2} \\ 1 & 1 & 1 \end{bmatrix}$$

**Thus:**  $\overline{A} = (0,0), \ \overline{B} = (0,\sqrt{2}), \ \overline{C} = (\frac{3\sqrt{2}}{2}, \frac{7\sqrt{2}}{2})$ 

## <u>H.W</u>.: Draw the vertices of the above example before and after the scaling?