

S₁-- Linear Transformations

التحويلات الخطية

Def :- let V and U be vector spaces over the field K . if $L : V \rightarrow U$ is function from V to U , then we say that L is **linear transformation** if

- (1) for all $U, V \in V \Rightarrow L(U + V) = L(U) + L(V)$
- (2) for $k \in K, U \in V \Rightarrow L(kU) = kL(U)$

ملاحظة :-

ان عملية الجمع $U + V$ خاصة بالفضاء V بينما عملية الجمع $L(U) + L(V)$ هي خاصة بالفضاء U وكذلك عملية الضرب .

Ex:- show that $L : R^3 \rightarrow R^2$ be defined by $L(U_1, U_2, U_3) = (U_1, U_2)$ is **linear transformation**

Sol :-

(1) let $U, V \in R^3 \Rightarrow U = (U_1, U_2, U_3)$ and $V = (V_1, V_2, V_3)$ by def

$$\begin{aligned} L(U + V) &= L((U_1, U_2, U_3) + (V_1, V_2, V_3)) \\ &= L((U_1 + V_1, U_2 + V_2, U_3 + V_3)) && (\text{by sum of vector}) \\ &= ((U_1 + V_1), (U_2 + V_2)) && (\text{by def of } L) \\ &= (U_1, U_2) + (V_1, V_2) \\ &= L(U_1, U_2, U_3) + L(V_1, V_2, V_3) \\ &= L(U) + L(V) \end{aligned}$$

(2) let $k \in R$

$$\begin{aligned} L(kU) &= L(k(U_1, U_2, U_3)) \\ &= L(kU_1, kU_2, kU_3) \\ &= (kU_1, kU_2) \\ &= k(U_1, U_2) \\ &= kL(U_1, U_2, U_3) \\ &= kL(U) \end{aligned}$$

by (1) and (2)

therefore , L is **linear transformation**

Ex :- (2) Let $L : R^3 \rightarrow R^2$ be defined by

$$L(U_1, U_2, U_3) = (U_1, U_1 + U_2 + U_3) . \text{ show that } L \text{ is linear transformation}$$

Sol :- (1) let $U, V \in R^3$

$$\begin{aligned} L(U + V) &= L((U_1, U_2, U_3) + (V_1, V_2, V_3)) \\ &= L(U_1 + V_1, U_2 + V_2, U_3 + V_3) \\ &= ((U_1 + V_1), (U_1 + V_1) + (U_2 + V_2) + (U_3 + V_3)) \\ &= (U_1 + V_1, (U_1 + U_2 + U_3) + (V_1 + V_2 + V_3)) \\ &= (U_1, U_1 + U_2 + U_3) + (V_1, V_1 + V_2 + V_3) \\ &= L(U_1, U_2, U_3) + L(V_1, V_2, V_3) \\ &= L(U) + L(V) \end{aligned}$$

$$\begin{aligned}
 (2) \text{ Let } K &\in \mathbb{R} \text{ and } U \in \mathbb{R}^3 \\
 L(K(U)) &= L(KU_1, KU_2, KU_3) \\
 &= KU_1, KU_1 + KU_2 + KU_3 \\
 &= K(U_1, U_1 + U_2 + U_3) \\
 &= KL(U)
 \end{aligned}$$

by (1) and (2) therefore L is linear transformation

Ex :- (3) let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be defined by $T(x, y) = (x, y+1)$. determine whether T is linear transformation

Sol :-

$$\begin{aligned}
 (1) \text{ let } V, U \in \mathbb{R}^2 &\implies T(V) = (V_1, V_2 + 1) \\
 &\quad T(U) = (U_1, U_2 + 1)
 \end{aligned}$$

$$\begin{aligned}
 T(V+U) &= T((V_1, V_2) + (U_1, U_2)) \\
 &= T((V_1 + U_1, V_2 + U_2)) \\
 &= (V_1 + U_1, V_2 + U_2 + 1)
 \end{aligned}$$

$$\text{but } T(V) + T(U) = (V_1 + U_1, V_2 + U_2 + 2)$$

$$T(V+U) \neq T(V) + T(U)$$

Then T is not linear transformation

S₂-- The Kernel and Range Of Linear Transformation

نواة و مدى التحويلات الخطية

Def :- let $L: V \rightarrow W$ be a linear transformation the *kernel* of L is the sub set of V consisting of all vectors V such that $L(v) = O_w$ and denoted by $\ker(L)$

$$\ker(L) = \{ v \in V : L(v) = O_w \}$$

(النواة:- مجموعه كل العناصر في V بحيث صورتها تساوي المتجه الصفر في W تحت تأثير الدالة الخطية (L))

Ex :- if $L: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be defined by $L(U_1, U_2, U_3) = (U_1, U_3)$ find $\ker(L)$

Sol :-

$$\begin{aligned}
 \ker(L) &= \{ U \in \mathbb{R}^3 : L(U) = O_{\mathbb{R}^2} \} \\
 &= \{ (U_1, U_2, U_3) : T(U_1, U_2, U_3) = (0, 0) \} \\
 &= \{ (U_1, U_2, U_3) : U_1 = 0, U_2 = 0 \} \\
 &= \{ (0, 0, U_3) \in \mathbb{R}^3, U_3 \in \mathbb{R} \}
 \end{aligned}$$

Ex :- (2) let $T: \mathbb{R} \rightarrow \mathbb{R}^2$ be defined by

$$T(U) = (U, 2U), \text{ find } \ker(T)$$

Sol :-

$$\begin{aligned}
 \ker(T) &= \{ U \in \mathbb{R} : T(U) = O_{\mathbb{R}^2} \} \\
 &= \{ U \in \mathbb{R} : (U, 2U) = (0, 0) \} \\
 &= \{ U \in \mathbb{R} : U = 0 \} \\
 &= \{ 0 \}
 \end{aligned}$$

Ex :- (3) let $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be defined by

$T(U_1, U_2, U_3) = (U_1 + U_2, U_2, U_1 - U_3)$, find $\ker(T)$

Sol :-

$$\begin{aligned}\ker(T) &= \{ U \in \mathbb{R}^3 : T(U) = 0_{\mathbb{R}^3} \} \\ &= \{ (U_1, U_2, U_3) \in \mathbb{R}^3 : T(U_1, U_2, U_3) = (0, 0, 0) \} \\ &= \{ (U_1, U_2, U_3) \in \mathbb{R}^3 : (U_1 + U_2, U_2, U_1 - U_3) = (0, 0, 0) \} \\ &= \{ (U_1, U_2, U_3) \in \mathbb{R}^3 : U_1 + U_2 = 0, U_2 = 0, U_1 - U_3 = 0 \} \\ &= \{ (U_1, U_2, U_3) \in \mathbb{R}^3 : U_1 = 0, U_2 = 0, U_3 = 0 \} \\ &= \{ (0, 0, 0) \}\end{aligned}$$

Ex :- (4) let $T : \mathbb{R}^4 \rightarrow \mathbb{R}^2$ be defined by

$T(x, y, z, w) = (x + y, z + w)$, find $\ker(T)$

Def:- let $L : V \rightarrow W$ is a linear transformation the **Range** of L is the set of all vectors in W that are images under L . of vectors in V .

$$\text{Range}(T) = \{ w \in W : v \in V \text{ s.t } T(v) = w \}$$

المدى :- مجموعة المتجهات في W والتي تكون صور لمتجهات من V تحت تأثير الدالة الخطية L

Theorem :- if $T : V \rightarrow W$ is linear transformation then

- (1) $\ker(T)$ is **subspace** of V .
- (2) $\text{Range}(T)$ is **subspace** of W .

Proof :- (1)

(a) let $U, V \in \ker(T)$

$$T(U) = 0, T(V) = 0$$

$$\begin{aligned}T(U + V) &= T(U) + T(V) \quad (\text{T. linear tr.}) \\ &= 0 + 0 \\ &= 0\end{aligned}$$

Then, $U + V \in \ker(T)$

(2) let $K \in \mathbb{R}$, $U \in V$

$$T(U) = 0$$

$$\begin{aligned}T(KU) &= K T(U) \\ &= K \cdot 0 \\ &= 0\end{aligned}$$

Thus, $KU \in \ker(T)$

By (1) and (2) $\ker(T)$ is subspace.

Ex :- let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ such that

$T(0, 1) = (1, 2)$, $T(1, 1) = (2, -2)$, then find $T(3, -2)$ and find $T(a, b)$?

Such that $S = ((0, 1), (1, 1))$ is spans of \mathbb{R}^2

Sol :-

S spans \mathbb{R}^2

Then , every vector in \mathbb{R}^2 is linear comb . of element of S .

$$K_1(0, 1) + K_2(1, 1) = (3, -2)$$

$$(0, K_1) + (K_2, K_2) = (2, -2)$$

$$(K_2, K_1 + K_2) = (3, -2)$$

$$K_2 = 3$$

$$K_1 + K_2 = -3 \implies K_1 = -5$$

$$(3, -2) = -5(0, 1) + 3(1, 1)$$

$$\begin{aligned} T(3, -2) &= T(-5(0, 1) + 3(1, 1)) \\ &= T(-5(0, 1)) + T(3(1, 1)) \\ &= -5T(0, 1) + 3T(1, 1) \\ &= -5(1, 2) + 3(2, -3) \\ &= (-5, -10) + (6, -9) \\ &= (1, -19) \end{aligned}$$

(2) to find $T(a, b)$

$$C_1(0, 1) + C_2(1, 1) = (a, b)$$

$$C_1 = b - a, C_2 = a$$

Then

$$(a, b) = (b - a)(0, 1) + a(1, 1)$$

$$\begin{aligned} T(a, b) &= T((b - a)(0, 1) + a(1, 1)) \\ &= T(b - a)(0, 1) + T(a(1, 1)) \\ &= (b - a)T(0, 1) + aT(1, 1) \\ &= (b - a)(1, 2) + a(2, -3) \\ &= (b - a, 2(b - a)) + (2a, -3a) \\ &= (b + a, 2b - 5a) \end{aligned}$$

Ex:- if $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is linear trans . and $T(1, 0) = (2, -2), T(0, 1) = (4, 1)$
find $T(3, 2)$ and $T(a, b)$?

بعد حل هذه المعادلة نحصل على

S₃.. Matrix Of Linear Transformation

مصفوفة التحويل

ملاحظة :- لاجداد مصفوفة التحويل (Matrix Of Linear Tran) ذات السعة $m * n$ بحيث

حيث

$$T: \mathbb{R}^n \implies \mathbb{R}^m$$

نفرض ان e_1, e_2, \dots, e_n قاعدة اعميادية فان

$$T(e_1), T(e_2), \dots, T(e_n)$$

تمثل اعمدة المصفوفة . A

Ex :- let $T: \mathbb{R}^2 \implies \mathbb{R}^2$ is L . transformation such that

$$T \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} x + 2x_2 \\ x_1 - x_2 \end{pmatrix}$$

Find a matrix A such that $T(x) = A x$.

Sol :-

Let $S = ((1, 0), (0, 1))$ be a basis of \mathbb{R}^3 then

$$T \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$T \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 2 \\ 1 & -1 \end{pmatrix}$$

Ex :- find (*Matrix Of Linear Tran .*) of $T : \mathbb{R}^3 \longrightarrow \mathbb{R}^4$ defined by

$$T \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} x_1 + 2x_2 \\ 3x_1 - x_2 \\ x_2 - x_3 \\ x_1 \end{pmatrix}$$

Sol :- let $S = \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$ be a basis of \mathbb{R}^3
Then

$$T \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \\ 0 \\ 1 \end{pmatrix}, T \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \\ 1 \\ 0 \end{pmatrix}, T \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ -1 \\ 0 \end{pmatrix}$$

اذن حسب تعريف مصفوفة التحويل الخطى تصبح مجموعة الصور لدالة T اعمده للمصفوفة A (مصفوفة التحويل الخطى T)

$$A = \begin{pmatrix} 1 & 2 & 0 \\ 3 & -1 & 0 \\ 0 & 1 & -1 \\ 1 & 0 & 0 \end{pmatrix} \quad 4*3$$